

LNS based Matheuristic for the Dial-a-Ride Problem

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Daily transportation service for disabled people by *GIHP* *Service Adapté*



Rhône Alpes



Medical-Social
Establishments
x160



Families
Children
x1000

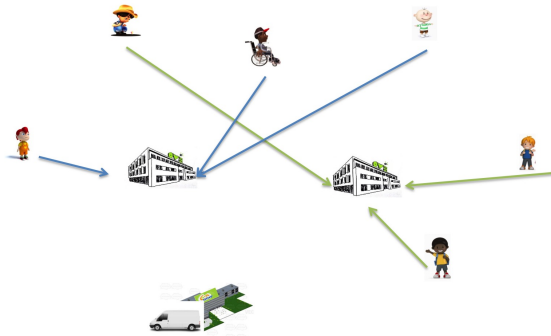


Transporter
vehicles
X182

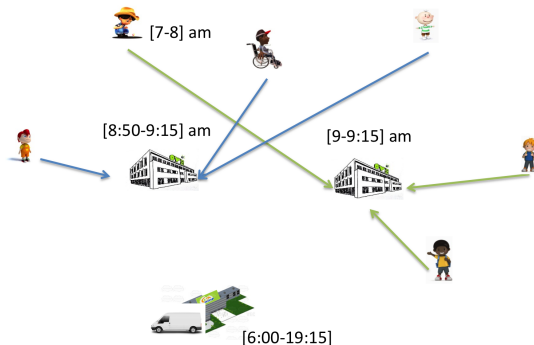
Dial-a-Ride Problem (DARP)



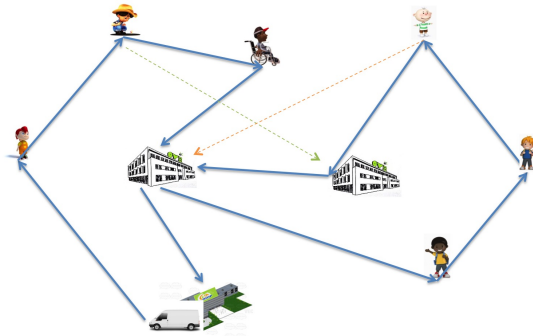
Dial-a-Ride Problem (DARP)



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Solution Methods for DARP

Auteur	Exact	Aprox	Instances	Solution methods
Gschwind and Irnich [2014]	X		C	Branch & Cut & Price
Ropke and Cordeau [2009]	X		C/R	Branch & Cut & Price
Braekers et al. [2014]	X		C	DA
Cordeau and Laporte [2003]		X	C	Tabu Search
Ropke and Pisinger [2006]		X	C/R	ALNS
Parragh et al. [2010]		X	C	VNS
Jain and Van Hentenryck [2011]		X	C	LNS-FFPA
Qu and Bard [2012]		X	PDP	GRASP
Masson et al. [2014]		X	C	ALNS
Braekers et al. [2014]		X	C	DA
Chassaing et al. [2016]		X	C/R	ELS
Parragh and Schmid [2013]	X	X	C	Hybrid Column Generation and LNS
Ritzinger et al. [2014]	X	X	C	Dynamic Programming LNS
Grangier et al. [2016]	X	X	VRP-CD	LNS-SPP

Instances: (C) Cordeau (R) Ropke & Pisinger.

Algorithm 1: Matheuristic LNS-SCP

Input: Problem data, Ω^- set of destroy operators, Ω^+ set of repair operators

Output: Best found solution s^*

1 s : Current solution, s' : Temporary solution

2 Pool of routes $\mathcal{J} \leftarrow \emptyset$

3 Generate initial solution s

4 **while** Stopping criterion not reached **do**

5 $s' \leftarrow s$

6 **Destroy quantity:** select a number Φ of requests to remove from s'

7 **Operator selection:** destroy operator $M^- \in \Omega^-$, repair operator $M^+ \in \Omega^+$

8 **Destroy:** Apply M^- to remove Φ requests of s'

9 **Repair:** Apply M^+ to reinsert requests

10 $\mathcal{J} \leftarrow \mathcal{J} \cup \text{routes}(s')$

11 **if** acceptance criterion is met **then**

12 $s \leftarrow s'$

13 **if** cost of s' is better than cost of s^* **then**

14 $s^* \leftarrow s'$

15 **if** SCP criterion is reached **then**

16 $s' \leftarrow \text{Solve Set Covering Problem}(\mathcal{J})$

17 update $s^* \leftarrow s'$ if s' is cheaper

18 Perform pool management

19 **return** s^*

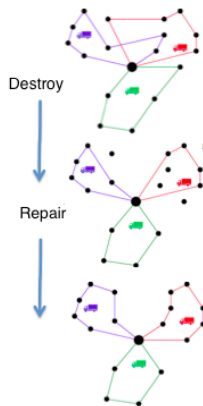


Figure: LNS

LNS Operators

The ALNS framework from Pisinger and Ropke [2007] suggests the following operators:

Destroy Operators

- Random Removal
- Historical Node-Pair Removal
- Historical Request-Pair Removal
- Worse Removal
- Route Removal (cluster)
- Distance Removal
- Time Removal
- Proximity Removal

Repair Operators

- Cheapest Insertion
- K-regret

LNS Operators

When combined with SCP for the DARP, experiments suggest to use:
Destroy Operators

- Random Removal
- Historical Node-Pair Removal
- Historical Request-Pair Removal
- Worse Removal
- Route Removal (cluster)
- Distance Removal
- Time Removal
- Proximity Removal

Repair Operators

- Cheapest Insertion
- K-regret

Set Covering Problem (SCP)

$\mathcal{J} = \{1, \dots, |\mathcal{J}|\}$ be the set of routes in the pool,

$v_t \in \mathbb{R}^+$ be the cost of route $t \in \mathcal{J}$,

$R_{rt} \in \{0, 1\}$ be 1 if request $r \in \mathcal{R}$ is served by route $t \in \mathcal{J}$ and 0 otherwise,

$y_t = 1$ if route $t \in \mathcal{J}$ is used in the solution and 0 otherwise.

$$\text{Objective} := \min \sum_{t \in \mathcal{J}} v_t y_t \quad (1)$$

s.t

$$\sum_{t \in \mathcal{J}} R_{rt} y_t \geq 1 \quad \forall r \in \mathcal{R}, \quad (2)$$

$$y_t \in \{0, 1\}. \quad (3)$$

Set Covering Problem (SCP)

Memory mechanism: Non-dominated routes are memorized at every LNS iteration.

Definition (Route dominance: route $\mathcal{A}$ dominates route $\mathcal{B}$)

if $\mathcal{A}$ visits the same set of nodes as $\mathcal{B}$ at a lower cost.

SCP Solving:

- The SCP is solved every η iterations
- MILP solver is used (time limit 3 secs, initialized with s^*)
- Current solution is updated only if SCP improves it.
- At the end, duplicates request are removed from SCP solution.

Pool management: If SCP solution was not optimal within the time limit, pool is cleared and filled again with the routes of s^* .

Comparison Performance: LNS-SCP vs ALNS vs LNS

Instance	BKS	LNS-SCP		ALNS		LNS	
		%GAP _{min}	%GAP _{Avg}	%GAP _{min}	%GAP _{Avg}	%GAP _{min}	%GAP _{Avg}
R1a	190.02	0.00	0.00	0.00	0.00	0.00	0.00
R2a	301.34	0.00	0.00	0.00	0.00	0.00	0.26
R3a	532	0.00	0.13	0.32	0.57	0.59	0.85
R4a	570.25	0.61	1.13	3.12	3.48	3.50	3.82
R5a	626.93	7.42	8.28	6.15	7.87	7.88	8.23
R6a	785.26	5.27	6.75	6.04	6.65	5.98	7.05
R7a	291.71	0.00	0.00	0.00	0.00	0.00	0.00
R8a	487.84	1.44	1.87	1.36	2.52	2.52	3.24
R9a	658.31	4.49	5.66	4.40	6.14	5.05	7.12
R10a	851.82	8.92	9.48	9.28	10.05	8.95	10.03
R1b	164.46	0.00	0.00	0.00	0.00	0.00	0.00
R2b	295.66	0.10	0.19	0.43	0.50	0.80	1.13
R3b	484.83	0.87	1.21	2.14	2.57	2.59	3.07
R4b	529.33	0.58	2.60	4.39	5.59	6.29	6.87
R5b	577.29	4.25	4.90	5.26	5.78	5.32	6.05
R6b	730.67	7.46	8.95	7.83	8.82	8.08	8.56
R7b	248.21	0.00	0.00	0.00	0.00	0.00	0.00
R8b	458.73	0.66	1.52	2.51	3.05	3.01	3.49
R9b	593.49	1.29	3.82	6.68	7.24	5.52	7.02
R10b	785.68	9.04	11.48	11.10	12.03	10.37	11.92
Average		2.62	3.40	3.55	4.14	3.82	4.44

Instances from Cordeau and Laporte [2003]. 5 mins evaluation over 5 runs.

LNS-SCP gains an small performance.

Comparison efficiency: LNS-SCP vs ALNS vs LNS

LNS-SCP gains a lot of efficiency!

	LNS-SCP		ALNS		LNS	
Instance*	t(sec)	t%	t(sec)	t%	t(sec)	t%
R1a	1.98	26%	7.69	100%	6.91	90%
R2a	51.84	29%	102.62	58%	177.19	100%
R3a	236.59	100%	194.49	82%	123.26	52%
R7a	16.75	63%	26.08	98%	26.52	100%
R1b	5.95	41%	14.45	100%	3.52	24%
R2b	107.80	49%	192.66	88%	218.60	100%
R7b	8.55	16%	31.58	59%	53.09	100%
Average		46%		84%		81%

t: Average time to find the BKS. Test in 5 mins over 5 runs.

* Instances where all three algorithms found a BKS.

Benchmarking: 5 mins test

LNS-SCP is competitive with dedicated algorithms!

		Jain and Van Hentenryck [2011]		Parragh and Schmid [2013]		Masson et al. [2014]		Ours	
		LNS-FFPA (5 runs)		HLNS (5 runs)		ALNS (5 runs)		LNS-SCP (5 runs)	
Instance	New BKS	Avg	% GAP_{Avg}	Avg	% GAP_{Avg}	Avg	% GAP_{Avg}	Avg	% GAP_{Avg}
R1a	190.02	190.77	0.40	190.02	0.00	190.02	0.00	190.02	0.00
R2a	301.34	304.45	1.03	303.63	0.76	301.98	0.21	301.34	0.00
R3a	532.00	547.15	2.85	536.77	0.90	536.74	0.89	532.70	0.13
R4a	570.25	595.05	4.35	581.41	1.96	588.37	3.18	576.72	1.13
R5a	626.93	662.56	5.68	643.72	2.68	655.02	4.48	678.83	8.28
R6a	785.26	832.74	6.05	837.01	6.59	824.21	4.96	838.29	6.75
R7a	291.71	292.86	0.39	291.93	0.08	291.71	0.00	291.71	0.00
R8a	487.84	505.15	3.55	498.44	2.17	500.30	2.55	496.96	1.87
R9a	658.31	711.60	8.09	697.22	5.91	691.45	5.03	695.57	5.66
R10a	851.82	911.18	6.97	908.12	6.61	903.35	6.05	932.54	9.48
R1b	164.46	164.46	0.00	164.46	0.00	164.46	0.00	164.46	0.00
R2b	295.66	301.67	2.03	297.99	0.79	300.58	1.66	296.24	0.19
R3b	484.83	504.69	4.10	495.02	2.10	499.26	2.98	490.68	1.21
R4b	529.33	566.48	7.02	540.76	2.16	554.96	4.84	543.08	2.60
R5b	575.64	610.33	6.03	607.17	5.48	604.28	4.98	605.55	5.20
R6b	730.67	785.13	7.45	772.21	5.69	780.71	6.85	796.08	8.95
R7b	248.21	248.31	0.04	248.21	0.00	248.21	0.00	248.21	0.00
R8b	458.73	477.75	4.15	473.19	3.15	472.35	2.97	465.71	1.52
R9b	593.49	633.51	6.74	620.39	4.53	617.22	4.00	616.16	3.82
R10b	784.30	857.95	9.39	874.36	11.48	844.48	7.67	875.88	11.68
Avg		535.19	4.32	529.10	3.15	528.48	3.17	531.84	3.42

Instances from Cordeau and Laporte [2003] in 5 mins over 5 runs.

Benchmarking: 50000 iterations

LNS-SCP is competitive with state of the art algorithms + 2 new BKS!

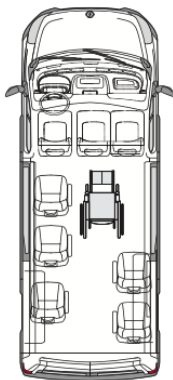
Paper	Parragh [2011]			Masson et al. [2014]			Braekers et al. [2014]			Chassaing et al. [2016]			Ours		
<i>BKS_{new}</i>	<i>GAP_{Avg}</i>	<i>GAP_{min}</i>	<i>T_{min}</i>	<i>GAP_{Avg}</i>	<i>GAP_{min}</i>	<i>T_{min}</i>	<i>GAP_{Avg}</i>	<i>GAP_{min}</i>	<i>T_{min}</i>	<i>GAP_{Avg}</i>	<i>GAP_{min}</i>	<i>T_{min}</i>	<i>GAP_{Avg}</i>	<i>GAP_{min}</i>	<i>T_{min}</i>
R1a	190.019	0.00	0.00	0.54	0.00	0.00	2.09	0.00	0.00	0.28	0.00	0.00	0.25	0.00	0.00
R2a	301.336	0.39	0.00	2.76	0.13	0.00	6.06	0.00	0.00	0.70	0.00	0.00	1.25	0.00	0.00
R3a	531.995	1.17	0.62	5.11	0.29	0.00	13.17	0.29	0.02	0.81	0.35	0.08	2.30	0.25	0.00
R4a	570.25	1.05	0.15	16.29	1.63	0.56	30.47	1.80	1.21	1.24	0.74	0.05	7.37	0.31	0.24
R5a	626.93	1.70	0.41	26.70	1.47	0.71	44.00	0.82	0.46	1.49	1.70	0.62	12.07	6.70	6.34
R6a	785.26	1.92	0.46	48.48	1.61	0.78	64.96	1.96	1.59	1.78	1.38	0.96	21.92	2.24	0.41
R7a	291.71	0.29	0.00	1.02	0.29	0.00	3.45	0.18	0.18	0.38	0.43	0.00	0.47	0.00	0.00
R8a	487.84	1.51	0.84	5.92	1.67	0.65	14.76	0.65	0.64	0.81	1.09	0.77	2.68	0.77	0.41
R9a	658.31	2.70	0.48	24.89	1.69	0.79	34.43	1.27	0.66	1.20	3.50	2.21	11.25	1.28	0.52
R10a	851.82	3.18	2.41	47.17	1.69	1.22	67.75	1.06	0.25	1.91	1.04	0.65	21.33	3.63	1.97
R1b	164.46	0.97	0.00	0.61	0.64	0.00	2.19	0.00	0.00	0.40	0.00	0.00	0.28	0.00	0.00
R2b	295.66	1.09	0.10	3.00	0.34	0.10	9.17	0.14	0.01	0.86	0.02	0.00	1.37	0.23	0.00
R3b	484.825	1.33	0.00	8.19	1.44	0.45	23.82	1.07	0.78	1.27	1.21	0.86	3.70	0.50	0.00
R4b	529.33	2.24	1.04	22.58	1.18	0.68	51.26	2.20	1.07	1.95	0.50	0.33	10.20	1.18	0.67
R5b	575.637	2.24	1.80	44.09	1.33	0.19	91.54	1.22	0.72	2.59	0.51	0.20	19.93	0.97	0.00
R6b	730.67	1.78	1.00	71.50	2.47	1.51	128.36	2.26	1.76	3.01	0.81	0.08	32.32	4.71	2.92
R7b	248.21	0.00	0.00	1.30	0.00	0.00	5.06	0.45	0.45	0.57	0.00	0.00	0.58	0.00	0.00
R8b	458.73	2.51	1.08	9.54	1.44	0.58	23.63	0.80	0.66	1.35	0.80	0.54	4.32	0.72	0.00
R9b	593.49	2.15	0.00	27.49	1.88	1.13	68.13	1.20	0.80	2.44	0.68	0.32	12.43	1.24	0.50
R10b	784.303	3.45	2.36	69.57	1.78	1.27	118.18	2.06	1.20	2.71	2.33	1.39	31.45	3.32	0.00
Avg	1.58	0.64	21.84	1.15	0.53	40.12	0.97	0.62	1.39	0.85	0.45	9.87	1.40	0.70	18.08
Nb. Best	7			6			3			6			7		

Benchmarking instances Cordeau and Laporte [2003] over 5 runs.

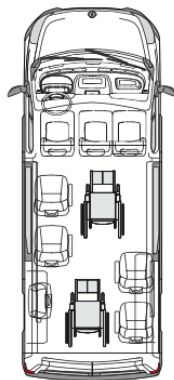
Contributions

- LNS-SCP framework for the DARP.
- Selection of LNS fundamental Operators.
- The SCP component increases the (A)LNS efficiency and performance.
- In the 5 mins benchmark provides competitive results for dedicated algorithms.
- In the 50000 iterations benchmark provides 2 new BKS and stands competitive against state of the art algorithms.

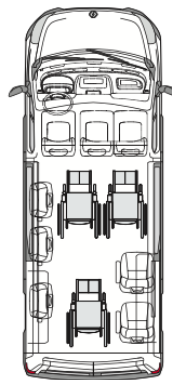
Perspectives: reconfigurable vehicles capacity



$$7 \text{ [standard seat icon]} + 1 \text{ [wheelchair icon]} = 8$$



$$6 \text{ [standard seat icon]} + 2 \text{ [wheelchair icon]} = 8$$



$$4 \text{ [standard seat icon]} + 3 \text{ [wheelchair icon]} = 7$$

Perspectives: regularity issues

- **Master Problem:** determine the set of daily solutions so that regularity is maximized.
- **Sub-problems:** Transportation plan for every mid-day.

	Lundi	Mardi	Mercredi	Jeudi	Vendredi
Matin	M1	M2	M3	M4	M5
Soir	S1	S2	S3	S4	S5

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November 3, 2016



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